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| --- | --- | --- | --- | --- | --- | --- | --- |
| S.No. | As a <<type of user>> | I want <<some goal>> | so that <<reason>> | Date introduced | Date considered for implementation | Developer responsible for | Current Status |
| 1 | Viewer | Draw the whole block | The environment of the run can be set up. | Jan 21, 2017 |  | Yifan Gu | Not started |
| 2 | Viewer | Draw open spaces | The environment of the run can be set up. | Jan 21, 2017 |  | Yifan Gu | Not started |
| 3 | Viewer | Set agents | The initial position of each agent can be set up. | Jan 21, 2017 |  | Yifan Gu | Not started |
| 4 | Viewer | Execute the algorithm step by step | Viewer can watch each step of patrolling carefully | Jan 21, 2017 |  | Sheng Zhang, Yifan Gu | Not started |
| 5 | Viewer | Execute the algorithm for a fixed number of times/steps | Viewer can speed some steps of patrolling | Jan 21, 2017 |  | Sheng Zhang, Yifan Gu | Not started |
| 6 | Viewer | View all historical runs of the algorithm | Viewer can choose any run and re-run it | Jan 21, 2017 |  | Chaohui Xu, Yifan |  |
| 7 | Viewer | Filter historical runs of the algorithm | View can easily find the run he/she want and re-run it | Jan 21, 2017 |  | Chaohui Xu, Yifan |  |
| 8 | Viewer | Select and re-run any historical runs of the algorithm | Viewer can view and analyze historical runs of the algorithm | Jan 21, 2017 |  | Sheng Zhang, Chaohui Xu, Yifan Gu | Not started |
| 9 | Viewer | View the details about the agents in each node in Graphical View | Viewer can know that for a particular node, which agents have visited it and how many times each agent has visited it | Jan 21, 2017 |  | Chaohui Xu, Yifan Gu | Not started |